## An Internet Book on Fluid Dynamics

## Derivation of relation between the time derivatives

Here we derive the relation between the Lagrangian and Eulerian time derivatives. Consider the Lagrangian fluid particle that occupies the point $O$ in some fixed Eulerian framework at time $t=0$. If the vector velocity of the fluid at this point and time is denoted by $\underline{u}$ then a short time $\delta t$ later the fluid particle will be displaced to the point $O^{\prime}$ where the vector $O O^{\prime}$ is given by $\underline{u} \delta t$. In a Cartesian framework with its origin at $O$, the coordinates of the point $O^{\prime}$ will be ( $\delta x=u \delta t, \delta y=v \delta t, \delta z=w \delta t$ ).

Now consider the Lagrangian and Eulerian time derivatives of some general transportable property in the fluid motion that we will denote by $Q$. By definition, the Eulerian time derivative of $Q$ at $O$ is simply $\partial Q / \partial t$. By contrast the Lagrangian time derivative, $D Q / D t$ will be given by

$$
\begin{equation*}
\frac{D Q}{D t}=\left[\frac{\{Q\}_{O^{\prime}, t=\delta t}-\{Q\}_{O, t=0}}{\delta t}\right]_{\delta t \rightarrow 0} \tag{Bad1}
\end{equation*}
$$

which, using the first two terms in a Taylor series expansion to write $\{Q\}_{O^{\prime}, t=\delta t}$ in terms of quantities evaluated at $O$ at time $t=0$, leads to

$$
\begin{equation*}
\frac{D Q}{D t}=\left[\frac{Q+\frac{\partial Q}{\partial t} \delta t+\frac{\partial Q}{\partial x} \delta x+\frac{\partial Q}{\partial y} \delta y+\frac{\partial Q}{\partial z} \delta z-Q}{\delta t}\right]_{\delta t \rightarrow 0} \tag{Bad2}
\end{equation*}
$$

where all quantities are now evaluated at $O$ and time $t=0$; all second and higher order terms in the Taylor series expansion have been omitted since they disappear when $\delta t \rightarrow 0$.

Substituting for $\delta x, \delta y$, and $\delta z$ using $\delta x=u \delta t, \delta y=v \delta t$, and $\delta z=w \delta t$ and then taking the limit as $\delta t \rightarrow 0$ leads to

$$
\begin{equation*}
\frac{D Q}{D t}=\frac{\partial Q}{\partial t}+u \frac{\partial Q}{\partial x}+v \frac{\partial Q}{\partial y}+w \frac{\partial Q}{\partial z} \tag{Bad3}
\end{equation*}
$$

Consequently the fundamental relationship between the Lagrangian and Eulerian time derivatives is

$$
\begin{align*}
\frac{D}{D t} \equiv \frac{\partial}{\partial t} & +u \frac{\partial}{\partial x}+v \frac{\partial}{\partial y}+w \frac{\partial}{\partial z} \\
& \equiv \frac{\partial}{\partial t}+u_{j} \frac{\partial}{\partial x_{j}} \\
& \equiv \frac{\partial}{\partial t}+(\underline{u} \cdot \nabla) \tag{Bad4}
\end{align*}
$$

where both the tensor and vector forms will be used in the material that follows.

